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PRA

Universitat de Barcelona

Universitat Oberta de Catalunva

## Multi-modal Social Signal Analysis for Predicting Agreement in Conversation Settings

15th ACM International Conference on Multimodal Interaction

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## Outline

## Motivation

Conversation settings

Methodology







#### Motivation Communication - Interaction

• Human language is essential in human social interactions.



- Human language is essential in human social interactions.
- Non-verbal communication is found within the human language through the gestures, and beyond the human speech [Pentland, 2008; McNeil, 2005].



#### **Motivation** Behavior analysis

• Understand what and how affect to participants mood.



- Understand what and how affect to participants mood.
- Multi-modal technologies allow to capture audio-RGBdepth data from conversational scenarios to analyze behavioral indicators appearing on the subjects [Marcos-Ramiro et. al., 2013].



## Outline



## Conversation settings

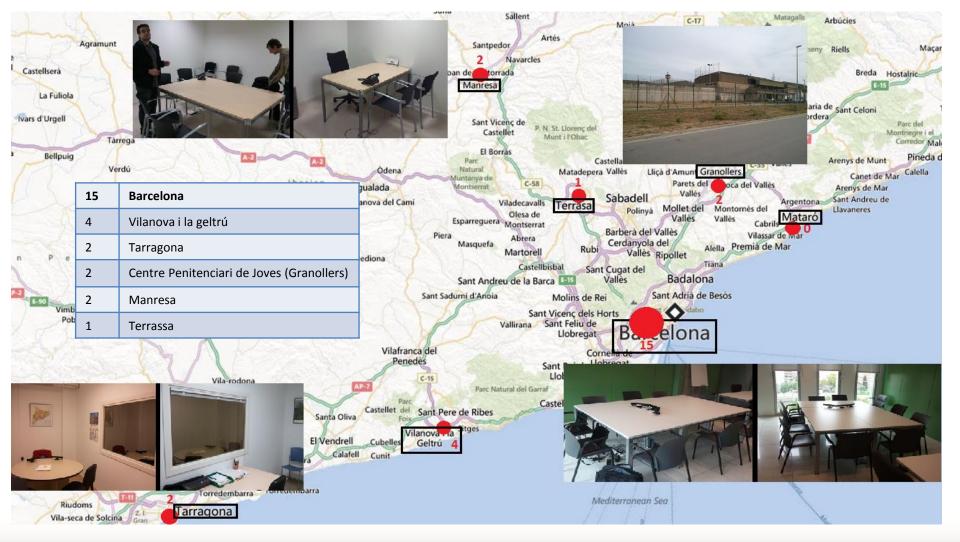
Methodology





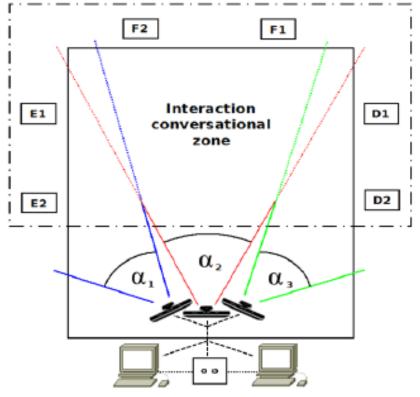


#### Conversation settings Recorded regions





#### **Conversation settings** Acquisition architecture



Ambient Intelligence Setup



- RGB-Depth Resolution:  $640 \times 480$ .
- Frames per second: 12.
- Distance to camera: 1-2 meters.
- Audio channels: 16 bit audio at sampling rate 16 kHz.



**Conversation settings** Mounted video sample

# Ciutat de la Justícia

19 de Setembre del 2012



## Outline

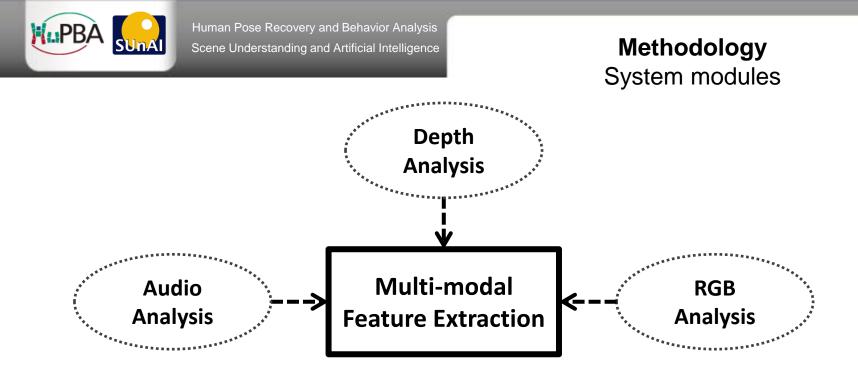
## Motivation

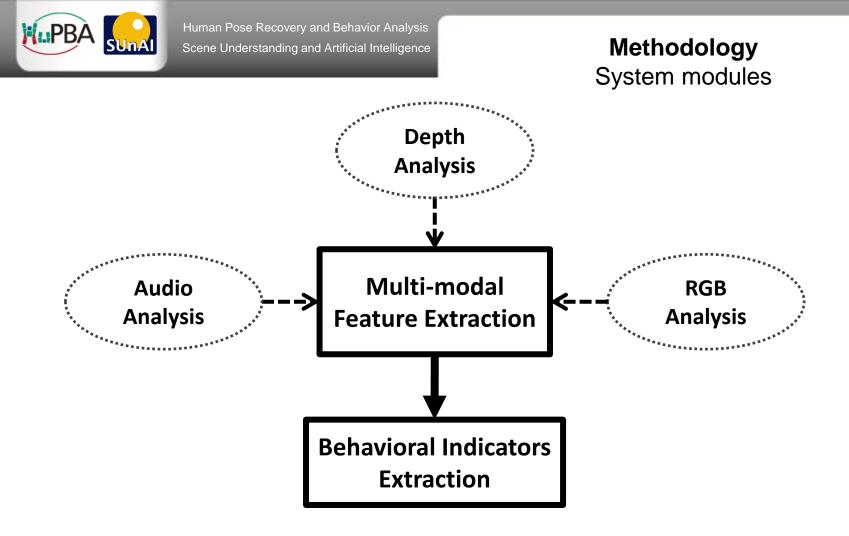
## Conversation settings

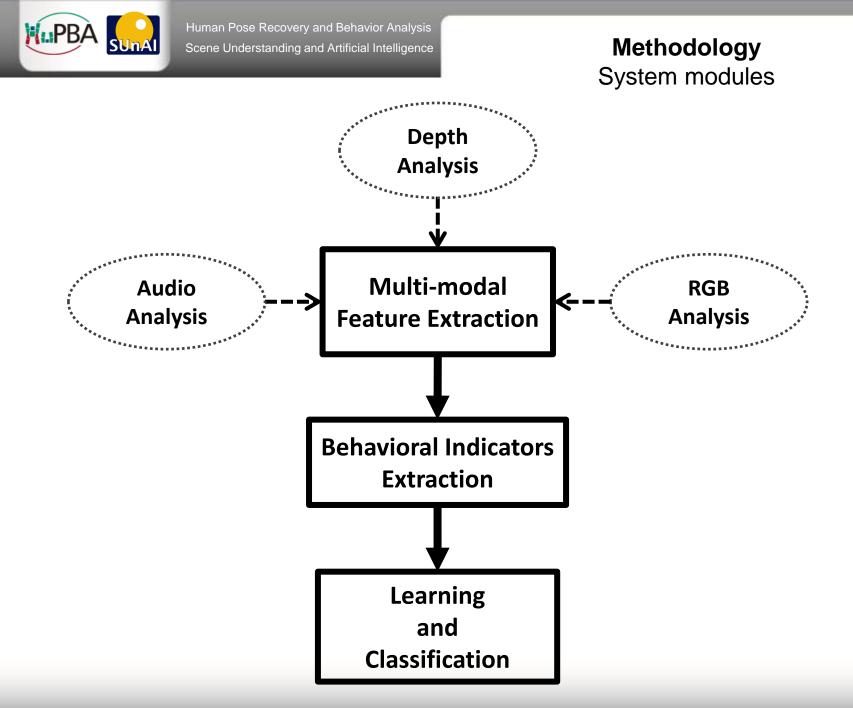
## Methodology

## Results

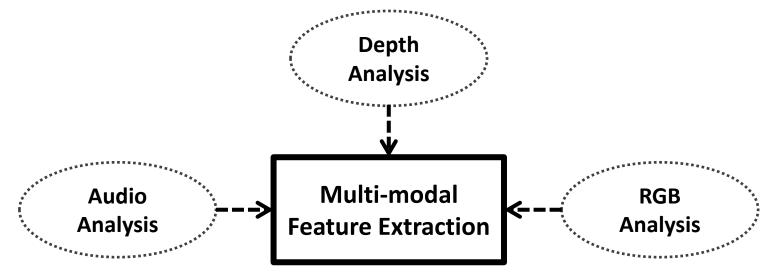
## **Conclusion**



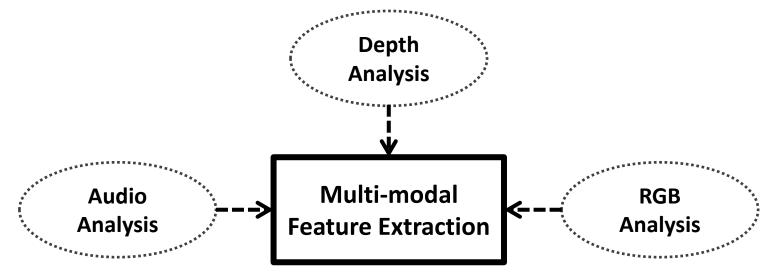




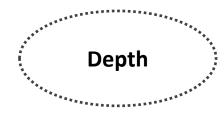












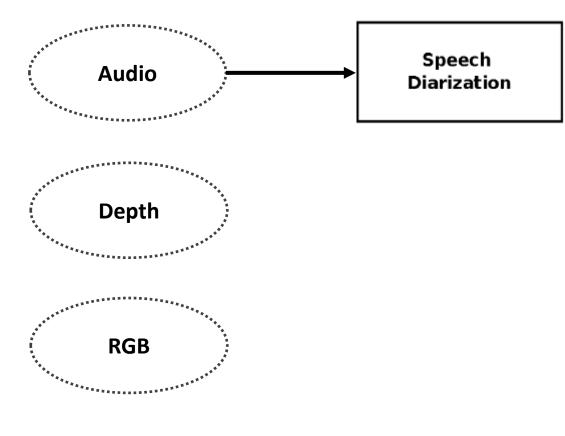




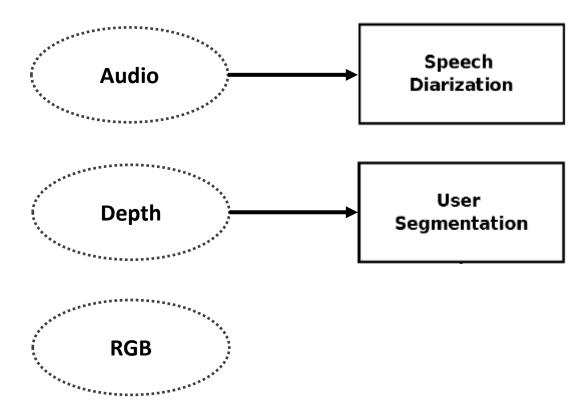


## Methodology

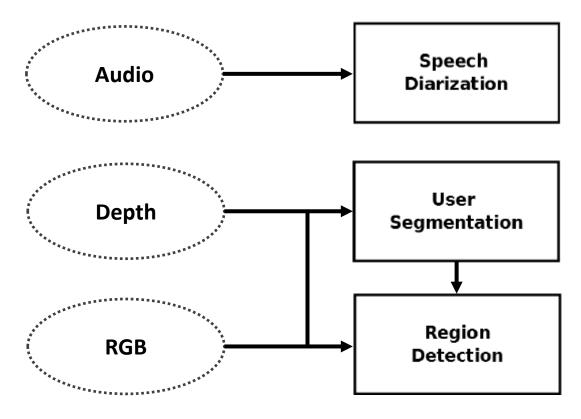
Multi-modal feature extraction



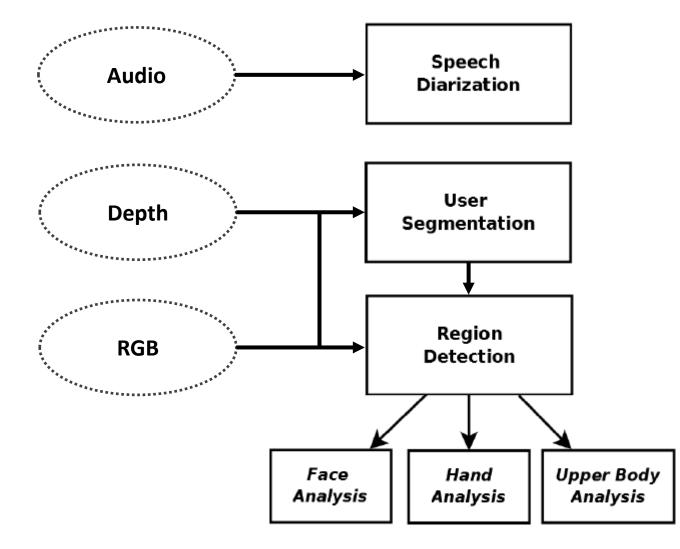




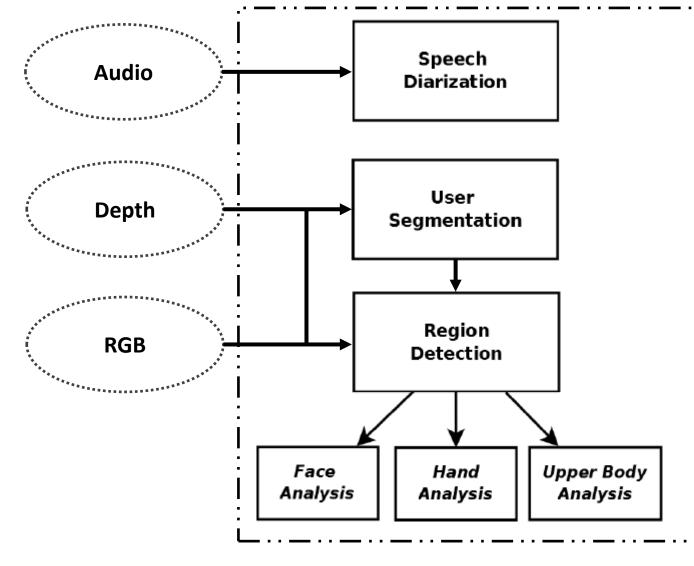






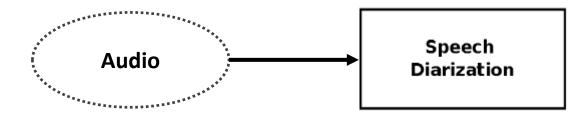






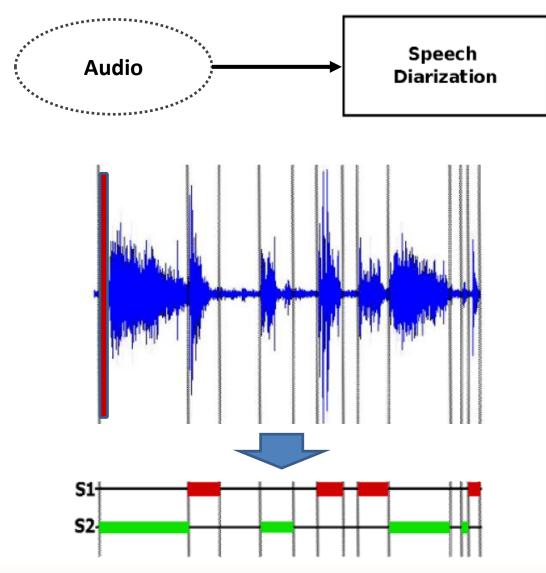


#### Methodology Speech diarization





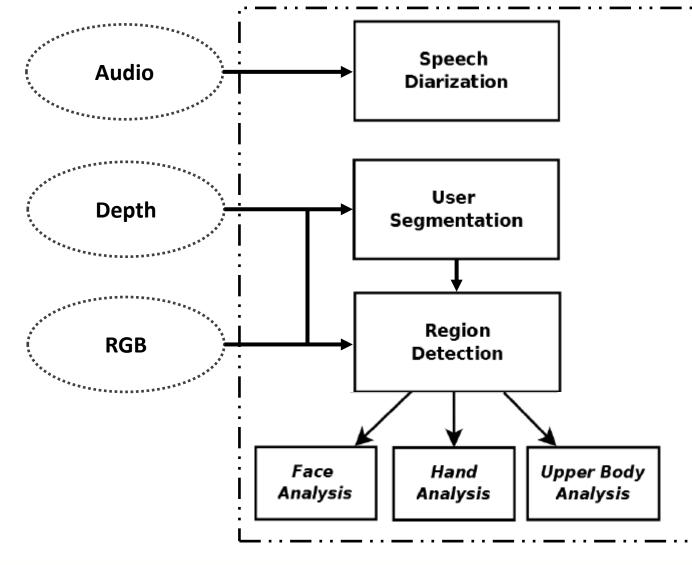
#### Methodology Speech diarization



- 12 MFCC per window.
- Hierarchical clustering.
- GMM speaker modelling.

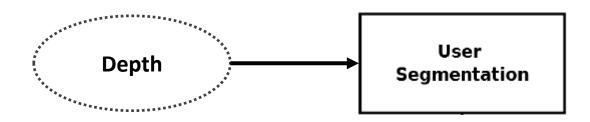
# Speaker segmentation identification





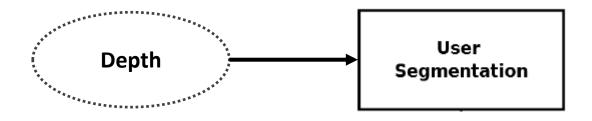


#### Methodology User Segmentation





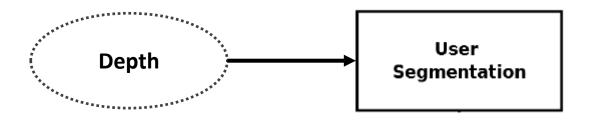
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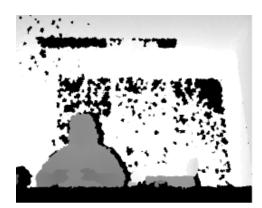




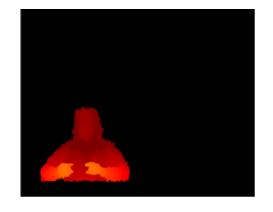


#### Methodology User Segmentation

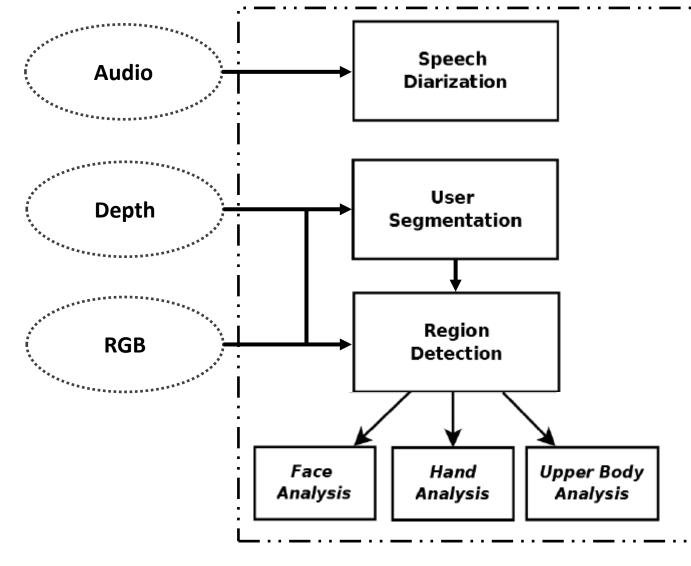




$$f_{\theta}(I,\dot{p}) = d_I \left(\dot{p} + \frac{\mu}{d_I(\dot{p})}\right) - d_I \left(\dot{p} + \frac{\nu}{d_I(\dot{p})}\right)$$
$$P(l|I,\dot{p}) = \frac{1}{T} \sum_{t=1}^T P_t(l|I,\dot{p})$$

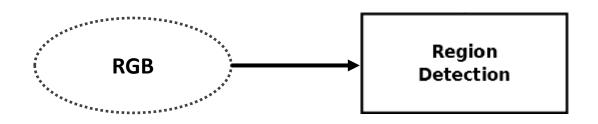








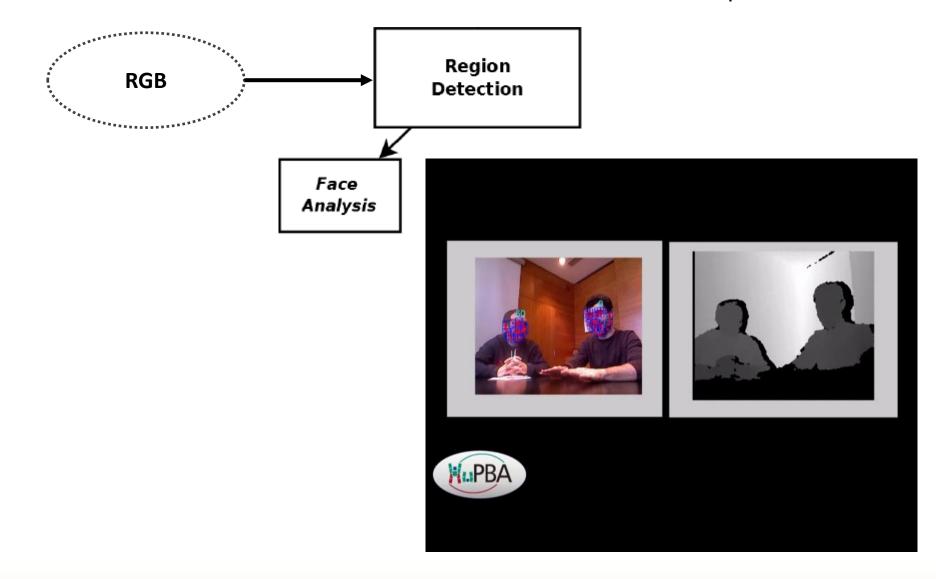
#### Methodology Region detection





#### Methodology

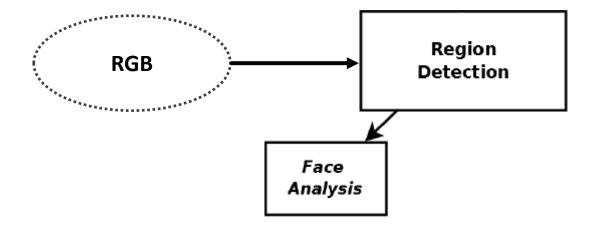
Face detection & head pose estimation



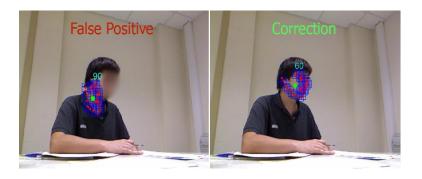


#### Methodology

Heuristics for face analysis

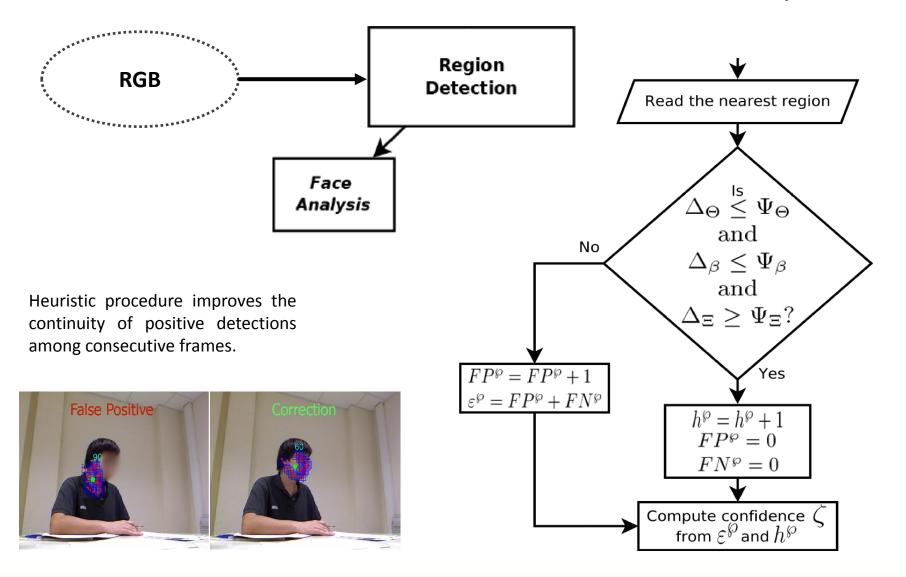


Heuristic procedure improves the continuity of positive detections among consecutive frames.



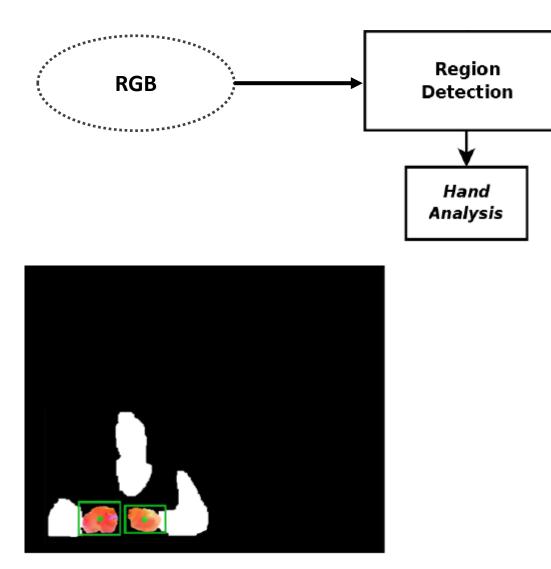


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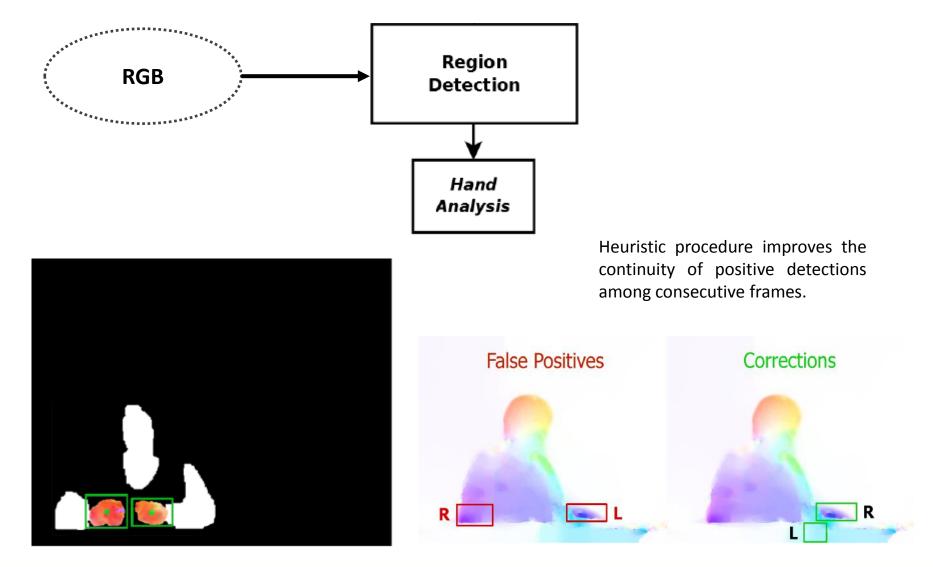


#### Methodology Hand analysis





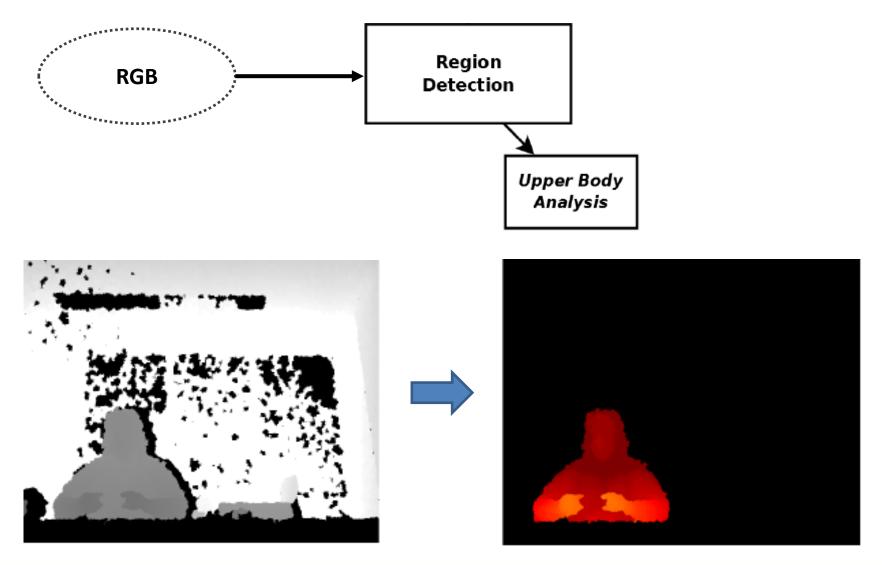
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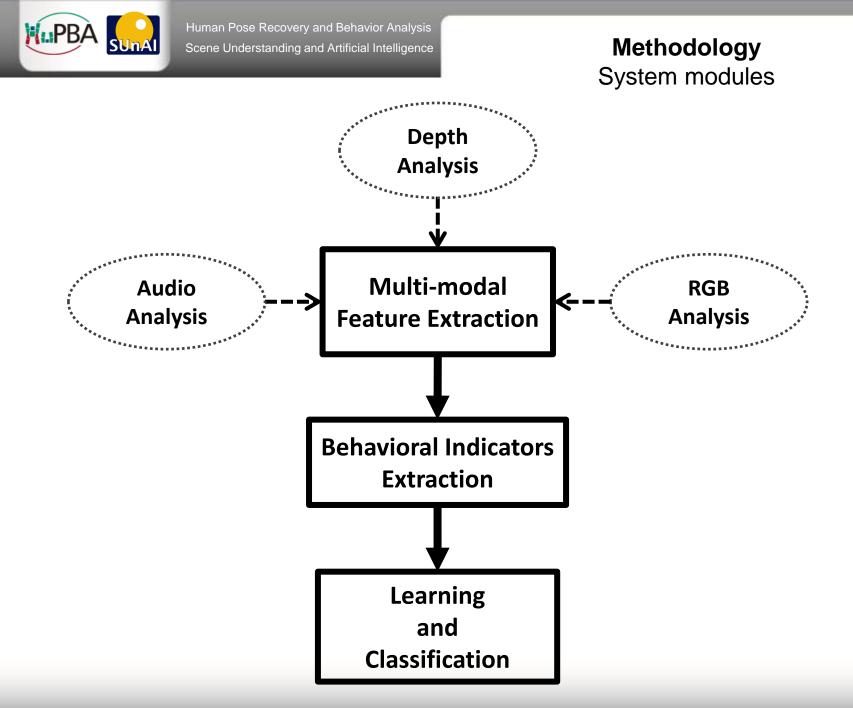




## Methodology

Upper body analysis





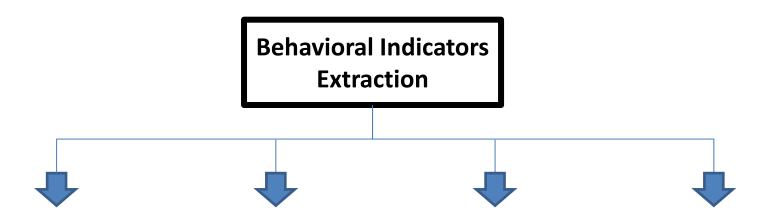


## Methodology Behavioral indicators extraction

Behavioral Indicators Extraction

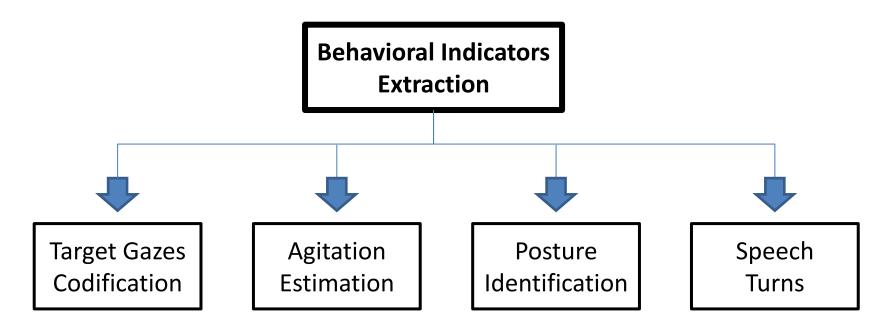


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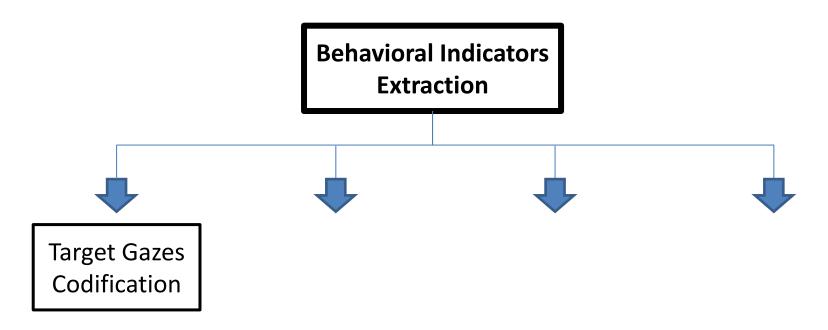




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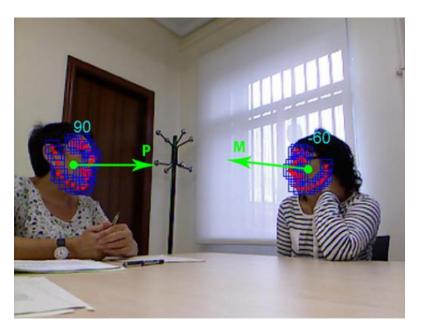






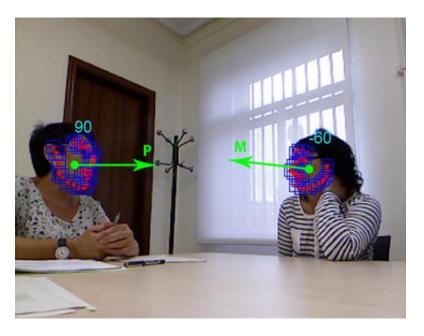


- P: Looking at the part, whether it is the offender as the victim. If there is more than one part (case of a joint encounter), P changes on the mediator column either by Off when it is the offender, or by Vic when it is the victim.
- M: looking at the mediator.
- MP: looking at the same part.
- MO: looking at the other part.





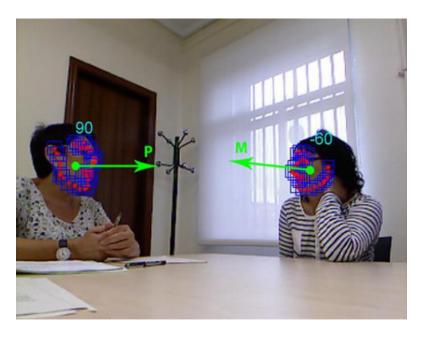
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	Mediator	Part
1 part with only 1 person	P   0   0	0   M   0
1 part with several people	P   0   0	$MP \mid M \mid 0$
2 parts with only 1 person on this part	Off   0   Vic	0   M   MO
2 parts with several people on this part	Off   0   Vic	MP   M   MO



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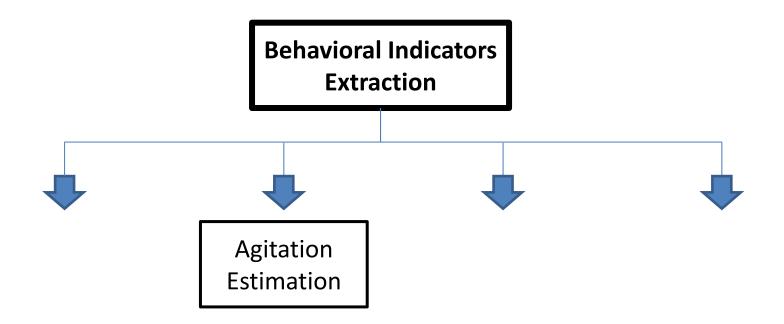


	Mediator	Part
1 part with only 1 person	P   0   0	$0 \mid \mathbf{M} \mid 0$
1 part with several people	P   0   0	$MP \mid M \mid 0$
2 parts with only 1 person on this part	Off   0   Vic	0   M   MO
2 parts with several people on this part	Off   0   Vic	MP   M   MO

Feature	Brief description	
$f_2$	This part looks at the other	
$f_3$	The other part looks at this part	L ₀⁄
$f_4$	This part looks at the mediator	70
$f_5$	The mediator looks at this part	



#### Methodology Agitation estimation





### Methodology Agitation estimation

Averaged agitation among *3D* positions of hands.

 $A_h = \frac{1}{\lambda} \sum_{\iota=1}^{\lambda} \Delta_h^{\iota}$ 

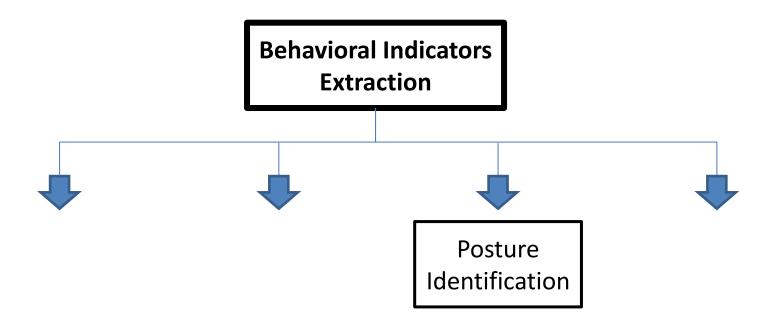
Accumulated average of optical flow produced by the upper body.

$$A_b = \frac{1}{\lambda} \sum_{\iota=1}^{\lambda} \bar{\sigma}_\iota$$

Feature	Brief description	]
$f_{14}$	Upper body agitation of this part	]_
$f_{15}$	Upper body agitation of this part while looking at the other	
$f_{16}$	Upper body agitation of this part while looking at the mediator	- %
$f_{17}$	Hands agitation of this part	
$f_{18}$	Hands agitation of this part while looking at the other	]
$f_{19}$	Hands agitation of this part while looking at the mediator	- %
$f_{20}$	Hands agitation of the mediator while looking at this part	[ 70
$f_{21}$	Hands agitation of the other part while looking at this part	]



### Methodology Posture identification

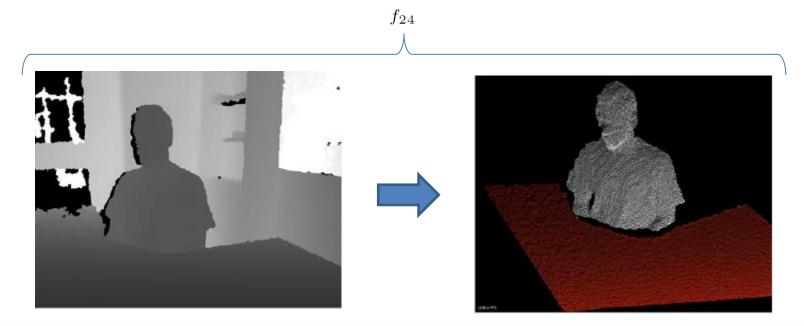




### Methodology Posture identification

Feature	Brief description	
$f_6$	Body posture inclination of this part	
$f_{22}$	This part have the hands together	
$f_{23}$	Hands of this part touches his/her face	
$f_{24}$	This part have the hands under the table	

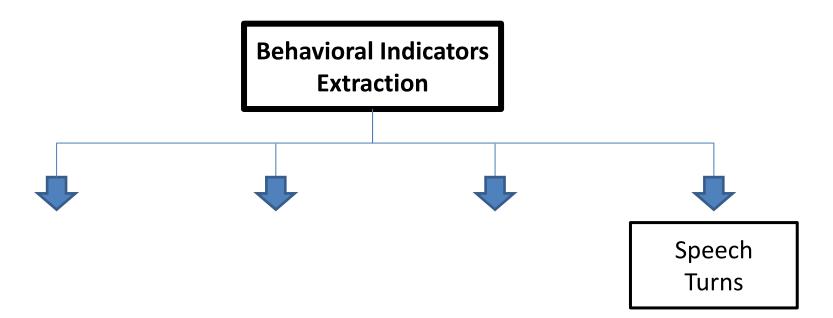
### *f*<sub>6</sub> : {'tilted backward', 'normal', 'tilted forward'}



[Rusu and Cousins, 2011] R. B. Rusu and S. Cousins, "3D is here: Point Cloud Library (PCL)," in IEEE International Conference on Robotics and Automation (ICRA), Shanghai, China, May 9-13 2011.



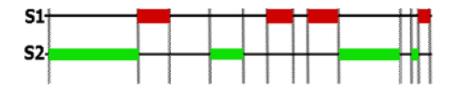
## Methodology Speech turns & interruptions





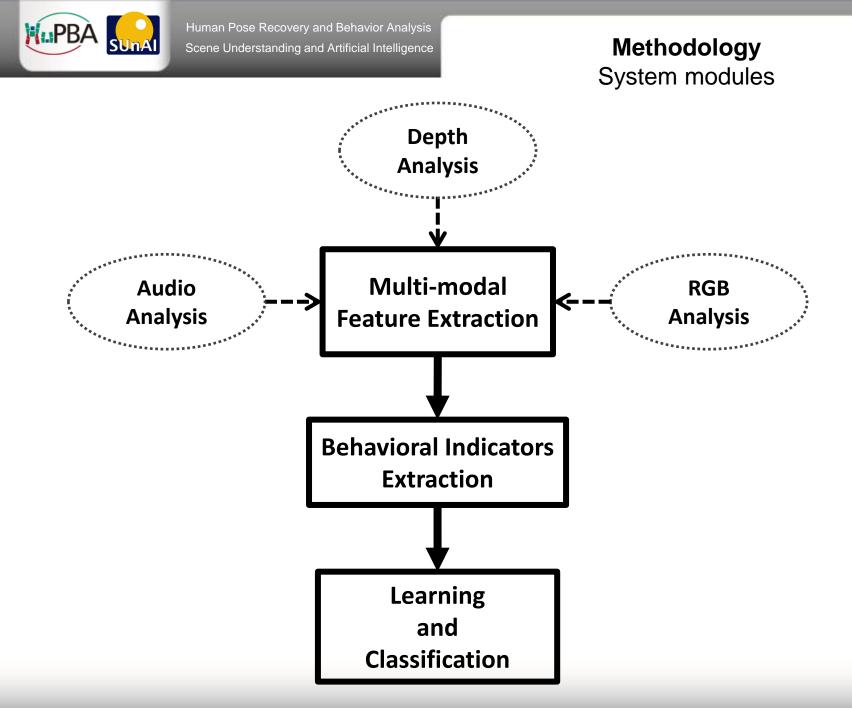
## Methodology Speech turns & interruptions

#### Speaker speech segments



Feature	Brief description	I	
$f_{25}$	Mediator speaking time	ſ٦	
$f_{26}$	Part speaking time	t L	0/
$f_{27}$	Other part speaking time	Ιſ	- %
$f_{28}$	Mediator speaking turns		
$f_{29}$	Part speaking turns	ſ٦	
$f_{30}$	Other part speaking turns	Ī	
$f_{31}$	Mediator interrupts this part	Ī	0/ of turns
$f_{32}$	This part interrupts the mediator	Ιſ	<ul> <li>% of turns</li> </ul>
$f_{33}$	This part interrupts the other part	Ī	
$f_{34}$	The other part interrupts this part		

[Escalera et. al., 2012] S. Escalera, X. Baró, J. Vitrià, P. Radeva, and B. Raducanu, "Social network extraction and analysis based on multimodal dyadic interaction," Sensors, vol. 12, no. 2, pp. 1702–1719, 2012.





## Methodology Learning and classification

Learning and Classification



Learning and Classification



# □ Each sample of the system is a part involved in a session.

Table 1: Summary of behavioral indicators defining each feature vector.

Feature	Brief description
$f_1$	Role within the conversation (victim, or offender)
$f_2$	This part looks at the other
<b>f</b> 3	The other part looks at this part
$f_4$	This part looks at the mediator
fs	The mediator looks at this part
<i>f</i> 6	Body posture inclination of this part
$f_7$	Gender of the mediator
$f_8$	Gender of this part
f9	Gender of the other part
f10	Age of the mediator
$f_{11}$	Age of this part
$f_{12}$	Age of the other part
$f_{13}$	Session type (individual/joint encounter)
$f_{14}$	Upper body agitation of this part
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$f_{21}$	Hands agitation of the other part while looking at this part
$f_{22}$	This part have the hands together
$f_{23}$	Hands of this part touches his/her face
f24	This part have the hands under the table
$f_{25}$	Mediator speaking time
$f_{26}$	Part speaking time
$f_{27}$	Other part speaking time
$f_{28}$	Mediator speaking turns
f29	Part speaking turns
<b>f</b> 30	Other part speaking turns
<b>f</b> 31	Mediator interrupts this part
$f_{32}$	This part interrupts the mediator
$f_{33}$	This part interrupts the other part
<b>f</b> 34	The other part interrupts this part



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Complementary features obtained from the surveys.

The rest of features are automatically obtained.

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Complementary features obtained from the surveys.

The rest of features are automatically obtained.

The response to predict by the classifiers is the accuracy when correlating the **agreement** produced among the parts with the impressions given by the experts.

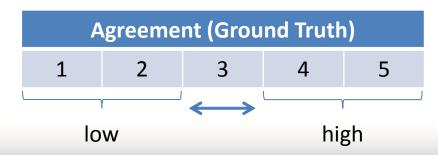


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## Methodology



## **Conclusion**



# **Results** Data and settings

### Acquired data

- ➤ 26 recorded sessions from multi Kinect<sup>™</sup> devices.
  - Average duration of sessions: 35 minutes.
    - From 20 minutes to 2 hours.
  - Resolution RGB-Depth:  $640 \times 480$ .
  - Frames per second: 12.
  - Distance to camera: 1-2 meters.
  - Audio channels: 16 bit audio at sampling rate 16 kHz.

15% of joint encounters  $\rightarrow$  2 parts. 85% of individual encounters  $\rightarrow$  1 part.



## **Results** Data and settings

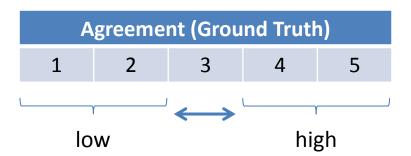
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## Validation

- 28 labeled samples.
- 34 features per sample.
- Leave-one-out validation is performed twice, computing the average for both grouping cases.





#### Table 2: Accuracy predicting agreement.

Label	Adaboost	CF	$\mathbf{FF}$	SVM
Agreement	71%	71%	75%	71%

□ There **exist** a **correlation** degree between the captured data and the information that we want to predict.



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- Grouping the **quantified** levels of expert **answers** adds an important weight to the final classification, fact that affects obtaining different predictions.
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- Grouping the **quantified** levels of expert **answers** adds an important weight to the final classification, fact that affects obtaining different predictions.
  - **Uncertainty** of the mediator when assigning the level could **add noise** to the overall data.
- □ The averaged frequency rate of **manual annotations** required is 1 for each 2000 frames, offering both **better accuracy** on the **continuity** of positive detections and a **periodic reduction** of the **search space**.



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Proposed a multi-modal framework for the analysis of non-verbal communication in real Victim-Offender Mediations.



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- Defined an automatic computation of behavioral indicators used as final features for learning and classification tasks.



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- Presented an heuristic procedure within the multi-modal feature extraction to improve the continuity of face/hands detection among consecutive frames.
- Defined an automatic computation of behavioral indicators used as final features for learning and classification tasks.
- Demonstrated the applicability as a tool for the experts, obtaining results upon 75% of accuracy predicting the agreement in conversational victimoffender mediation processes based on the ground truth defined by the experts.



### **Conclusion** Future work

□ Increase the overall data.



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□ Include local behavioral features, which will provide information about the instant of time where the behavior takes place (early or latest stages of the conversational session).



**Conclusion** Future work

## Increase the overall data.

- □ Include local behavioral features, which will provide information about the instant of time where the behavior takes place (early or latest stages of the conversational session).
- Extend the binary agreement classification problem to a continuous, regression, ranking, or multi-classification tasks, where a more fine agreement prediction could be achieved.



**Conclusion** Future work

## Increase the overall data.

- □ Include local behavioral features, which will provide information about the instant of time where the behavior takes place (early or latest stages of the conversational session).
- □ Extend the binary agreement classification problem to a continuous, regression, ranking, or multi-classification tasks, where a more fine agreement prediction could be achieved.
- □ Include more system observations (i.e. ground truth), assigned from a behavioral perspective, such as dominance, or engagement.

# Thank You!

## Multi-modal Social Signal Analysis for Predicting Agreement in Conversation Settings

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